

[6262]-326R

T.E. (Robotics & Automation)

FLEXIBLE MANUFACTURING SYSTEMS

(2019 Pattern) (Semester - II) (311510(A))

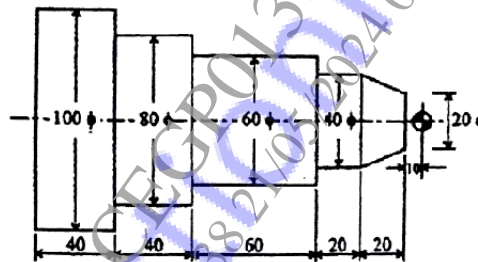
Time : 2½ Hours]

[Max. Marks : 70

Instructions to the candidates:

- 1) Solve Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6, Q.7 or Q.8.
- 2) Neat Diagram must be drawn wherever necessary.
- 3) Assume Suitable data if necessary
- 4) Use of Logarithmic Table, Slide rule or electronic pocket calculator is allowed.
- 5) Figure to the right indicates full marks.

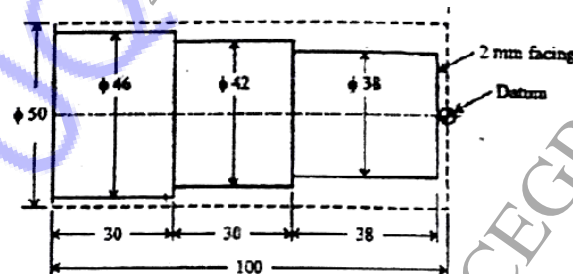
- Q1) a) Define NC machine and write the advantages of NC machine system over manual methods. [8]
- b) Prepare part programming of following component. [9]



All dimensions in mm.

OR

- Q2) a) Discuss the several word functions in Numerical Control systems. Discuss the advantages of DNC over NC/CNC. [8]
- b) Prepare part programming of following component. [9]

Raw workpiece = $\phi 50 \times 100$ mm

_____ (Dotted line) = Raw workpiece

_____ (Continuous line) = Final part (Finished part)

All the Dimensions are in mm.

Q3) a) What is a material requirement planning? Explain the various inputs to the MRP system? [9]

b) Explain the concept of ERP. [9]

OR

Q4) a) What is computer aided inspection (CAI) and how can we control quality with the help of CAI? [9]

b) Explain the term Rapid Product Development and Manufacture. [9]

Q5) a) Explain the basic components of a robotic system. [9]

b) What is robot? explain the benefits of using industrial robots. [9]

OR

Q6) a) Explain types of AGV and their principal of working. [9]

b) Explain the following terms : [9]

i) Unit load AS/RS

ii) Mini load AS/RS

iii) Carousel AS/RS

Q7) a) Give the concept of Tool Management. [8]

b) Describe Tool Preset Identification and Data Transfer. [9]

OR

Q8) a) What are the different types of tool strategies? Explain Each. [8]

b) Draw and explain block diagram offered detection in vibration. [9]
