

[6269]-422

T.E. (Robotics and Automation) (Insem.)

ARTIFICIAL INTELLIGENCE FOR ROBOTICS

(2019 Pattern) (Semester - II) (311509 A)

Time : 1 Hour]

[Max. Marks : 30

Instructions to the candidates:

- 1) Answer Q.1 or Q.2, Q.3 or Q.4.
- 2) Neat diagrams must be drawn wherever necessary.
- 3) Figures to the right side indicate full marks.
- 4) Use of calculator is allowed.
- 5) Assume suitable data if necessary.

Q1) a) What are features of uninformed search algorithms? Explain with suitable example any one uninformed search algorithm. [8]

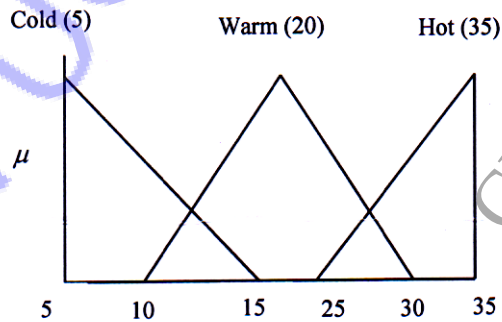
- b) In genetic algorithm, the variable x_1 is coded 1101 and variable x_2 is coded 1001. Determine the value of objective function $x_1^2 - 10x_2$ if $-4 \leq x_1, x_2 \leq 3$. [7]

OR

Q2) a) What is Hidden Markov Model? What are its components? [8]

- b) Demonstrate with suitable example application of Bayesian networks in robotics and automation? [7]

Q3) a) For the figure shown below, determine the membership values for temperature = 29° C. [7]



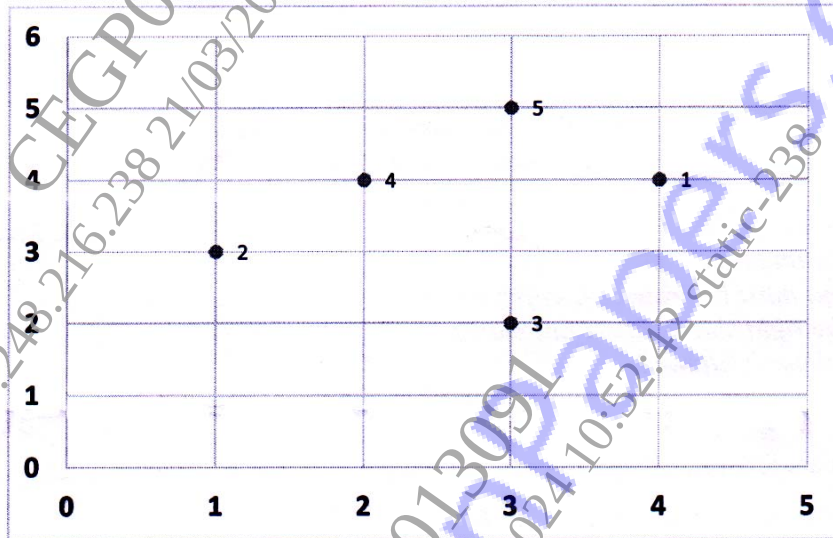
P.T.O.

- b) For the following data, use linear regression to determine the equation of the best fit line. [8]

x	3	2	1	4	6
y	5	4	4	7	6

OR

- Q4) a) Use K-Means Algorithm to create two clusters considering point 1 and 2 as initial centres. Perform two iterations. [8]



- b) In a feed forward network the connections between input and hidden nodes as shown below. If $w_1 = 0.20$, $w_2 = 0.10$, $w_3 = 0.12$ and $w_4 = 0.26$, bias = 0.25. Determine net input to h_1 and net output of h_1 if input 1 (i_1) = 0.4 and input 2 (i_2) = 0.2. Use sigmoid activation function. [7]

