

Total No. of Questions : 4]

SEAT No. :

PE577

[Total No. of Pages : 2

[6578]-50

S.E. (Production and Industrial Engineering/Production Sandwich/
Robotics and Automation) (Insem)

ENGINEERING MATHEMATICS - III
(2019 Pattern) (Semester - III) (207007)

Time : 1 Hour]

[Max. Marks : 30

Instructions to the candidates:

- 1) Attempt Q.1 or Q.2, Q.3 or Q.4.
- 2) Figures to the right side indicate full marks.
- 3) Assume suitable data wherever necessary.
- 4) Use of electronic pocket calculator is allowed.

Q1) a) Solve any two.

[10]

i) $\frac{d^2y}{dx^2} + y = \sec x$ (variation of parameters).

ii) $(1 - D^2)y = x^4$.

iii) $x^2 \frac{d^2y}{dx^2} - 4x \frac{dy}{dx} + 6y = x^5$.

b) Solve the simultaneous equations.

[5]

$$\frac{du}{dx} + v = \sin x ; \frac{dv}{dx} + u = \cos x.$$

OR

Q2) a) Solve any two.

[10]

i) $\frac{d^2y}{dx^2} - y = e^{5x}$ (variation of parameters).

ii) $(D^2 - 3D + 2)y = \sin x$.

iii) $x \frac{d^2y}{dx^2} + \frac{dy}{dx} = -x$.

b) A body weighing $W = 20\text{N}$ is hung from a spring. A pull of 40N will stretch the spring to 10 cm . The body is pulled down to 20 cm below the static equilibrium position and then released. Find the position and velocity as function of time. [5]

P.T.O.

Q3) a) Find the Laplace transform of $e^{-2t} (3 \cos 6t - 5 \sin 6t)$. [5]

b) Find the inverse Laplace transform of $F(s) = \frac{1}{s(s^2 + 4)}$. [5]

c) Using Fourier integral representation show that [5]

$$\int_0^{\infty} \left[\frac{a^2 \sin a\lambda}{\lambda} + \frac{2a \cos a\lambda}{\lambda^2} - \frac{2 \sin a\lambda}{\lambda^3} \right] \cos \lambda x \, d\lambda = \begin{cases} \frac{\pi}{2} x^2 & , \quad 0 < x < a \\ 0 & , \quad x > a \end{cases}$$

OR

Q4) a) Find the Laplace transform of: $\frac{e^{-3t} - e^{-2t}}{t}$ [5]

b) Find the Fourier sine transform of $f(x) = e^{-x}$. [5]

c) Solve the integral equation $\int_0^{\infty} f(x) \sin \lambda x \, dx = \begin{cases} 1 - \lambda & , \quad 0 \leq \lambda \leq 1 \\ 0 & , \quad \lambda \geq 1 \end{cases}$ to find $f(x)$. [5]

