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SEAT No. :

**PA-33**

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**S.E. (Production and Industrial Engineering/Production  
Sandwich/Robotics and Automation)  
ENGINEERING MATHEMATICS - III  
(2019 Pattern) (Semester - I) (207007)**

*Time : 1 Hour*

*[Max. Marks : 30*

*Instructions to the candidates:*

- 1) Attempt Q.1 or Q.2, Q.3 or Q.4.
- 2) Figures to the right side indicate full marks.
- 3) Assume Suitable data wherever necessary.
- 4) Use of electronic pocket calculator is allowed.

**Q1) a) Solve any two.**

**[10]**

i)  $(D^2 + 3D + 2)y = e^{e^x}$  (variation of parameter).

ii)  $\frac{d^2y}{dx^2} - 2\frac{dy}{dx} + y = x^2 e^{3x}$ .

iii)  $(1+x)^2 \frac{d^2y}{dx^2} + (1+x) \frac{dy}{dx} + y = 4 \cos[\log(1+x)]$ .

b)  $\frac{dx}{dt} + y = e^t$

$-\frac{dy}{dt} + x = e^{-t}$ .

**[5]**

OR

**Q2) a) Solve any two:**

**[10]**

i)  $\frac{d^2y}{dx^2} + y = \operatorname{cosec} x$  (variation of parameter).

ii)  $x^2 \frac{d^2y}{dx^2} - 2x \frac{dy}{dx} - 4y = x^4$ .

iii)  $(D^2 - 7D + 10)y = e^{2x} \sin x$ .

b) A body of weight  $w = 1$  N is suspended from spring stretches it 4 cm. If the weight is pulled down 8 cm below the equilibrium position and then released. Set up the differential equation. Find the position and velocity as function of time  $t$ .

**[5]**

*P.T.O.*

**Q3) a)** Find the Laplace transform of:  $e^{-t} \sin t$  [5]

**b)** Find the inverse Laplace transform of:  $F(s) = \frac{s}{s^2 + 6s + 25}$  [5]

**c)** Using Fourier integral representation show that

$$\int_0^\infty \frac{(1 - \cos \lambda\pi)}{\lambda} \sin \lambda x d\lambda = \begin{cases} \pi/2 & , \quad 0 < x < \pi \\ 0 & , \quad x > \pi \end{cases} . \quad [5]$$

OR

**Q4) a)** Find the Laplace transform of:  $\frac{\cos 6t - \cos 4t}{t}$  [5]

**b)** Find the Fourier cosine transform of  $f(x) = \frac{\pi}{2} e^x$  [5]

**c)** Solve the integral equation.  $\int_0^\infty f(x) \cos \lambda x dx = \begin{cases} \frac{1}{\lambda} & 0 \leq \lambda \leq 1 \\ 0 & \lambda > 1 \end{cases} . \quad [5]$

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