

Total No. of Questions : 6]

SEAT No. :

P5809

[Total No. of Pages : 2

**B.E./Insem/Oct.-560**

**B.E. (Electrical)**

**Control System - II**

**(2015 Pattern) (Semester - I)**

*Time : 1 Hour]*

*[Max. Marks : 30*

*Instructions to the candidates:*

- 1) *Answer any one question from each pair of questions : Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6.*

- Q1)** a) Draw and explain configuration of Basic Digital Control System. [6]  
b) What is holding device? Explain the operation of zero order hold circuit. [4]

OR

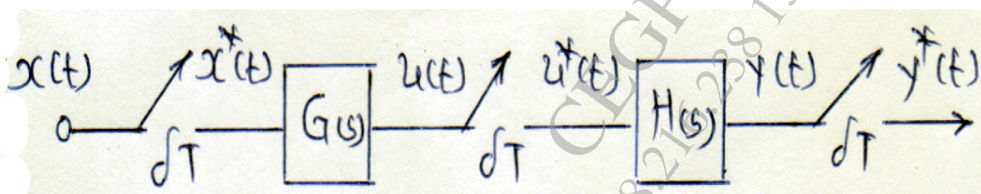
- Q2)** a) What are the advantages and limitations of Digital Control System? [6]  
b) Discuss various practical aspects of choice of sampling rate. [4]

- Q3)** a) Calculate  $y(k)$  if  $y(0)=1$  and  $y(1)=0$  and  $y(k)$  satisfies the difference equation  $Y(k+2)+3y(k+1)+2y(k)=u(k)$ . Where  $u(k)$  is unit step sequence. [6]

- b) State and prove Linearity and Time shifting property of Z-transform.[4]

OR

- Q4)** a) Find pulse transfer function of cascaded elements shown [6]



- b) Derive an expression for Pulse Transfer Function of ZOH using transfer function of ZOH. [4]

**P.T.O.**

- Q5) a)** Explain 'Direct digital programming' of realization of digital controller. [6]
- b) Illustrate stability analysis of closed loop system in Z-plane using Jury's test. [4]

OR

- Q6) a)** Determine the stability using Bilinear transformation of the system whose characteristic equation is [6]

$$5Z^2 - 2Z + 2 = 0$$

- b) Discuss mapping between S-Plane and Z-Plane. [4]

