Total No. of Questions : 8]

## P2943

## [5669] 532 T.E. (Electrical Engineering) ELECTRICAL MACHINES - II (2015 Pattern) (End Sem.)

*Time : 2<sup>1</sup>/<sub>2</sub> Hours]* 

[Max. Marks : 70

[6]

[7]

[Total No. of Pages : 2

**SEAT No. :** 

Instructions to the candidates:

- 1) Answer Q1 or Q2, Q3 or Q4, Q5 or Q6, Q7 or Q8.
- 2) Neat diagrams must be drawn wherever necessary.
- 3) Figures to the right indicate full marks.
- 4) Use of non-programmable scientific calculators is allowed.
- 5) Assume suitable data if necessary.

Q1) a) Derive the emf equation of alternator.

- b) What is significance of short circuit ratio, explain
- c) A 3-ph, 3300V 50Hz delta connected synchronous motor has synchronous reactance Xs = 18 Ω/ph and negligible resistance, It draws 800 kw while working at pf = 0.8 leading. Calculate [7]
  - i) Excitation emf &
  - ii) Power angle  $\delta$
- *Q2*) a) Why synchronous motor is not self starting? How to make it self starting, explain.

OR

- b) Why rotating magnetic field is preferred over stationary field of alternator. [7]
- c) Using OCC & SOC of alternator, explain the mmf method of finding voltage regulation at lagging, leading and unity p.f [7]
- Q3 a) State the various methods of speed control of 3-ph induction motor on stator and rotor side. explain v/f method. [8]
  - b) Why the name variable reluctance stepper motor? Explain the principle of operation with neat schematic diagram switching circuit and truth table for 1-ph on mode, 2-ph on mode & half stepping. [10]

*P.T.O.* 

- Explain the construction, principle of operation and characteristics of **Q4**) a) PMDC motor. Also state its applications. [8]
  - Compare variable reluctance stepper motor & permanent magnet stepper b) motor. [6]
  - A single stack, 3-ph, variable reluctance stepper motor has step angle c) 7.5°. Find its number of stator and rotor poles. [4]
- Why d.c. series motor does not work satisfactorily on a.c. supply. Sug-**Q5**) a) gest suitable modifications to improve its performance. [8]
  - Explain construction and principle of working of universal motor. [8] b) OR
- Compare conductively and inductively compensated ac series motor. State **Q6**) a) the applications of compensated ac series motor. [8]
  - Universal motor has  $R = 30 \Omega$ , L = 0.5H, when connected to 250v dc b) supply, draws 0.8 A & run at 2000 rpm. Find speed, torque, p.f. and efficiency, when connected to 250, 50Hz, ac supply, drawing the same current. Assume rotational losses = 15W[8]
- Why 1-ph induction motor is not self starting? Prove the same using **07**) a) double field revolving theory [8]
  - Explain the operation of single value capacitor start and run 1-ph b) induction motor. State its advantages. How to reverse its direction of rotation? Show by circuit diagram. **T8**1

## OR

With neat schematic diagram, explain the working of shaded pole induc-**Q8**) a) tion motor. State its applications. [8]

A 500w, 230v, 50Hz 1-ph induction motor has winding parameters Zm =b)  $4.5 + j3.7 \Omega$  (main winding impedance) and auxiliary winding impedance  $Zs = 9.5 + j 3.5 \Omega$ . Calculate the value of starting capacitor required to have maximum starting torque. [8]

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